

DEMO: An Open Research Framework for Optical Data Center Networks

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ABSTRACT

Optical data center networks (DCNs) have emerged as a promising design for cloud network infrastructure. However, research in this field is constrained by the requirement for specialized hardware and software stacks and the high engineering barriers of building optical testbeds. To address these challenges, we present an experimental platform that can realize diverse optical DCN architectures in a plug-and-play manner. We demonstrate the ease of realizing different architectures with Python scripts and show performance comparisons of running end-to-end cloud applications.

CCS CONCEPTS

• Networks \rightarrow Data center networks; Programmable networks; Network experimentation;

KEYWORDS

Data Center Networks, Optical Networks

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1 INTRODUCTION

Optical data center networks (DCNs) have arisen as a promising cloud network infrastructure design in the post Moore's law era for merchant silicon. Over the years, numerous optical DCN architectures using different optical switching hardware have been proposed [4, 6–11, 15–17, 19–22, 24–26], particularly the recent trend of traffic-oblivious optical DCNs that use high-speed optical circuit switches (OCSes) to rotate circuit connections between Top-of-Rack switches (ToRs) according to a predefined topology schedule [4, 5, 16, 17].

However, network and system research for optical DCNs is fundamentally constrained by the underlying optical hardware. For one thing, each optical DCN architecture requires specialized hardware and software stacks, obscuring innovation across domains. For another, due to the high engineering barrier of building optical



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Table 1: Framework User APIs.

Category	APIs	
Topology	<pre>connect(ToR1, port1, ToR2, port2, slice)</pre>	
	round_robin(#ToRs, #ports)	
	<pre>round_robin_offset(#ToRs, #ports)</pre>	
	round_robin_dimension(#ToRs, #ports, h)	
Routing	routing(routing_fn)	fn_direct(src, dst, slice)
	neighbors(ToR, slice)	<pre>fn_vlb(src, dst, slice)</pre>
	earliest_path(src, dst,	fn_ebs(src, dst, slice)
	slice, max_hop)	fn_opera(src, dst, slice)
	entries(paths, lookup_type,	<pre>fn_hoho(src, dst, slice)</pre>
	multipath_policy)	<pre>fn_ucmp(src, dst, slice)</pre>
Monitoring	buffer_usage(ToR)	
	<pre>bandwidth_usage(ToR, port)</pre>	
	drop rate(ToR)	

testbeds, evaluation of architecture-specific software solutions has to rely on home-grown simulators [4, 5, 16] or limited host-based emulation without an actual network fabric [18].

This work aims to bridge the gap between the diverse optical DCNs architectures and the lack of a unified experimental platform. We present a general framework that enables the plug-andplay realization of different optical architectures. Towards that, we abstract the fundamental building blocks for optical DCNs, including a programmable ToR system, a connection toolbox, and a network management plane with configuration and monitoring APIs. We demonstrate the simplicity of realizing different optical architectures with customized topology and routing using Python scripts of approximately 50 lines of code. We also show side-by-side performance comparisons of software solutions across hardware architectures running end-to-end cloud applications.

2 USER API

We define API functions, as listed in Table 1, for users to program high-level network protocols as Python scripts without worrying about the low-level system implementation.

Topology APIs. The primitive function for topology configuration is *connect()*. It adds an optical circuit between two ToRs through their ports in a time slice when the circuit stays still. Using this primitive, we provide built-in functions to generate topology schedules for existing optical DCN architectures, including the *round-robin* schedule enumerating connections across ToR pairs [4, 17], and round-robin variants such as the Opera [16] schedule with a port *offset* in circuit rotation and *h-dimensional* round-robin in EBS [3, 23]. Users can define customized topology schedules in the same way, such as the random connections exemplified in Code 1c. Our framework compiles the user-defined schedule into OCS connections and guides the optical controller to set them up in specified time slices.

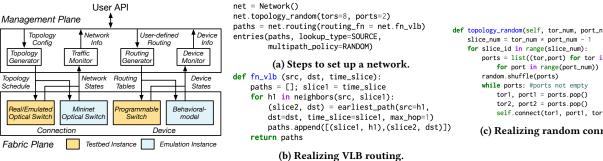


Figure 1: System diagram.

Routing APIs. Despite the diversity of routing algorithms for optical DCNs, we define a signature prototype, *routing_fn()*, that returns a set of paths for a prospective packet from a source ToR to a destination ToR in a particular time slice. The prototype is passed to routing() to generate all paths for all source-destination pairs in all time slices. We materialize the prototype for existing routing algorithms, including direct-path [17], VLB [4, 17], EBS [3, 23], Opera [16], HOHO [14], and UCMP [13], and allow users to implement customized routings following the signature format.

We also provide helper functions: neighbors() that returns connected neighbors for a ToR in a time slice, and earliest path() that returns the first path between a source ToR and a destination ToR since a given time slice. As maximizing throughput and minimizing latency are common objectives for optical DCNs, these helper functions serve as building blocks for specific routing algorithms, and Code 1b shows how VLB routing is implemented with them.

Finally, we offer entries() to translate paths into lookup table entries and load them onto each ToR. The framework supports source routing and per-hop lookup, with entries compiled accordingly. For multi-path routing, runtime path selection policy is needed. We enable random [4], flow-size-based [13], and queue-occupancybased [3, 4] selection as required by existing routing algorithms. Monitoring APIs. Our framework also exposes telemetry APIs for monitoring the network performance, such as the buffer usage, bandwidth usage, and packet drop rate of a ToR, and we will extend

3 FRAMEWORK DESIGN

them as future requirements arise.

Fig. 1 illustrates the system diagram for our framework. It consists of the management plane and the fabric plane. The management plane is responsible for network configuration and monitoring, through the user APIs described in §2. The fabric plane mainly comprises the ToR system implemented on programmable switches, along with connectivity management of the OCSes and the integral host system. The host system uses the VMA [2] high-performance userspace library to implement flow pausing [17] and flow aging [13] as required by some routing algorithms.

Our framework can operate in either a testbed environment with actual devices or an emulation environment on Mininet, lowering the hardware barrier for researchers and students. The testbed mode supports various types of OCSes, as well as emulated ones over programmable switches.

As the key component of the framework, the ToR system realizes three major functionalities: (1) time synchronization, (2) routing def topology_random(self, tor_num, port_num) ports = list((tor,port) for tor in range(tor_num) self.connect(tor1, port1, tor2, port2, slice_id)

(c) Realizing random connections.

Code 1: Code snippets of network applications using the APIs.

lookup, and (3) time-scheduled packet forwarding. For (1), we synchronize the ToRs with the optical controller over the varying optical circuits and achieve 28ns sync accuracy. For (2), we abstract a generic routing table format that matches a packet's arrival time slice and destination ToR to determine the departure time slice and egress port for sending the packet. For (3), we leverage the queue pausing feature of Tofino2 switches [12] to buffer packets when the departure time slice is later than the arrival time slice.

4 DEMONSTRATION

We demonstrate our framework on a testbed with 3 Intel Tofino2 switches and 4 servers, each with a ConnectX-6 dual-port NIC. We virtualize 2 physical switches into 4 logical ToRs each, and create 2 virtual hosts on each server by splitting the NIC interfaces into separate namespaces. To support various optical DCN architectures, we emulate OCSes on a Tofino2 switch with tunable time slice durations. Our setup thus contains 8 logical ToRs, each connected to a logical host with a 100Gbps downlink and to the OCSes with 4 10Gbps uplinks to mimic oversubscription in production DCNs.

Architecture implementation with the user APIs. We first demonstrate how our framework simplifies the implementation of optical DCN architectures. As shown in Code 1a, an architecture can be populated with just a few lines of Python code by calling API functions for the topology and routing schemes. We demonstrate the effect of each line of code, by visualizing the generated topology schedule and showing the lookup entries loaded to each ToR.

Code 1b and 1c dive into the implementation of topology and routing functions. In Code 1b, the built-in API fn_vlb() realizes twohop routing. Hop 1 is via possible ToRs directly connected to the source, obtained using neighbors(). Hop 2 is over the earliest direct circuit from each intermediate ToR to the destination, by calling earliest_path(). Code 1c shows a self-defined topology function to create random connections throughout time slices, by drawing randomly from unused ports and adding circuits through connect(). Side-by-side comparison running applications. We implement existing topology and routing methods as shown above and perform side-by-side performance comparisons between then with real applications. We generate latency-sensitive traffic with Memcached [1] and generate throughput-intensive traffic with iPerf. The framework enables logging of traffic statistics, such as flow completion times (FCTs). We demonstrate FCT distributions across different routing solutions. We observe that under 50μ s time slices, HOHO exhibits 27% and 88% reduction in 99th percentile FCT for Memcached traffic compared to Opera and VLB, respectively.

DEMO: An Open Research Framework for Optical Data Center Networks

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